

M2250 F15 TEST 1 SOL.

10:42

1. (a) $-x_1 + 2x_2 + x_3 = 4$
 (5) $2x_1 + x_2 + 8x_3 = 7$
 $3x_1 - x_2 + 7x_3 = 3$

(b) (5)
$$\begin{bmatrix} -1 & 2 & 1 & 4 \\ 2 & 1 & 8 & 7 \\ 3 & -1 & 7 & 3 \end{bmatrix}$$

(c) (10)
$$\begin{array}{l} \xrightarrow{\times -1} \\ \xrightarrow{+2R_1} \\ \xrightarrow{+3R_1} \end{array} \left[\begin{array}{ccc|c} 1 & -2 & -1 & -4 \\ 0 & 5 & 10 & 15 \\ 0 & 5 & 10 & 15 \end{array} \right] \begin{array}{l} \\ \xrightarrow{\times 1/5} \\ \xrightarrow{-R_2} \end{array} \left[\begin{array}{ccc|c} 1 & -2 & -1 & -4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{+2R_2}$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 3 & 2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ -2 \\ 1 \end{bmatrix}$$

(d) (5) $\begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$

(e) (5) $x_3 \begin{bmatrix} -3 \\ -2 \\ 1 \end{bmatrix}$

10:49

2. (a) (5) $T \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3+2+2 \\ 3+4+1 \\ 6+2+1 \end{bmatrix} = \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix}$

(b) (5) $\begin{bmatrix} 1 & 1 & 2 \\ 1 & 2 & 1 \\ 2 & 1 & 1 \end{bmatrix}$ (c) $\begin{array}{l} \xrightarrow{-R_1} \\ \xrightarrow{-2R_1} \end{array} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & -1 & -3 \end{bmatrix} \begin{array}{l} \xrightarrow{-R_2} \\ \xrightarrow{+R_2} \end{array} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & -4 \end{bmatrix}$ (5) YES

10:52

3. (a) Solution is $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix}$ or $-2\vec{v}_1 + 3\vec{v}_2 + \vec{v}_3 = 0$

(b) v_3 is dependent on v_1, v_2 so eliminate it. Others have pivots
 so $\{v_1, v_2, v_4\}$

(c) $v_3 = 2v_1 - 3v_2$

(d) No. can't solve $Av = b$ for every b because there is no pivot in row 4.

10:55

4. $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & h \\ 1 & 1 & -2 \end{bmatrix} \xrightarrow[-R_1]{-2R_1} \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & h-6 \\ 0 & -1 & -5 \end{bmatrix} \xrightarrow{-3R_3} \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & h-6+15 \\ 0 & -1 & -5 \end{bmatrix}$

$$h+9=0 \quad \text{or} \quad \boxed{h=-9}$$

10:57

5. $x_1(u-v) + x_2(v-w) + x_3(u-w) = 0$ gives
 $(x_1+x_3)u + (-x_1+x_2)v + (-x_2-x_3)w = 0$

Since $\{u, v, w\}$ is lin. indep. this implies $\begin{matrix} x_1 + x_3 = 0 \\ -x_1 + x_2 = 0 \\ -x_2 - x_3 = 0 \end{matrix}$

Now $\begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{bmatrix} \xrightarrow{+R_1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \xrightarrow{+R_2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

so the system has non-zero solutions. Not lin. indep.

11:00

6. $u+2v = 2(u+v) - 3u$ so $T(u+2v) = 2T(u+v) - 3T(u)$
 $= \begin{bmatrix} 2 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ -3 \end{bmatrix}$

11:01